

AVATAR – Advanced Virtual Aptitude and Training Application in Real-time

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Project partners



UGoe - University of Göttingen, Germany (Project lead)



IfADo - Leibniz Research Center for Working Environment and Human Factors, Germany



NIBIO

NORWEGIAN INSTITUTE OF
BIOECONOMY RESEARCH

NIBIO - Norwegian Institute for Bioeconomy Research, Norway



Optea, Sweden



skogforsk

Skogforsk - Forestry Research Institute of Sweden, Sweden



Skogkurs - Forestry Extension Institute, Norway

Landesbetrieb Wald und Holz
Nordrhein-Westfalen



WH-NRW - Forestry and Timber North Rhine-Westphalia, Germany

Mar 2019 – Oct 2022 (8 months extension)

Introduction

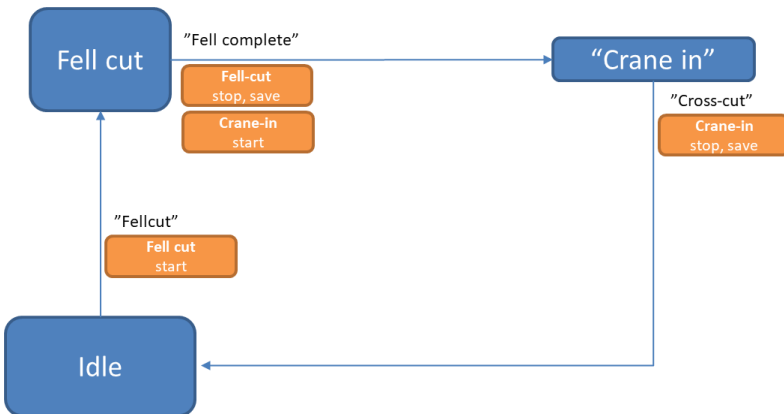
- ❖ **Main objective: Reduce training and skill demands on new machine operators and also mental workload on experienced operators**

Therefore:

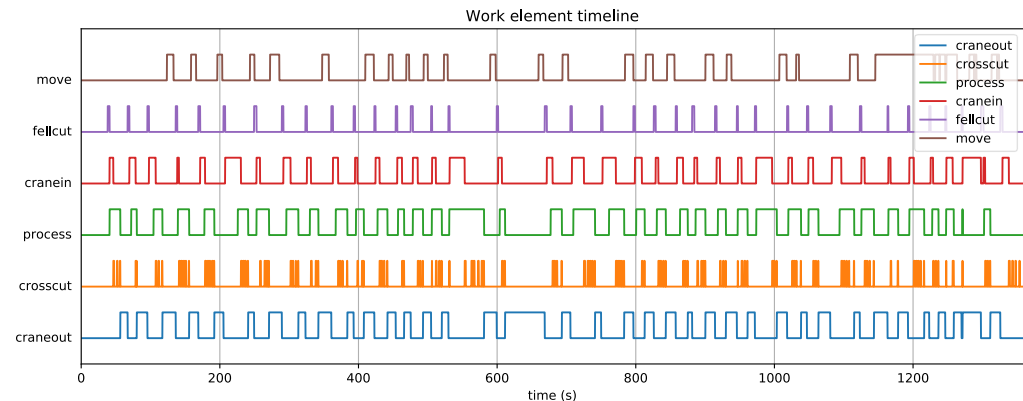
- **Investigate operators' need for feedback** and definitions for high performance and quality of work
- **Develop and implement sensors** to detect machine position and movement
- **Investigate several aspects** to improve log positioning, crane movement, bucking and harvester head measurements
- **Design a Digital Coach** that gives feedback about performance and quality of work
- **Install head-up display** in the cabin to show helpful information

Results – Defining the basics

❖ Algorithms for automated work phase detection



Depictions: Skogforsk



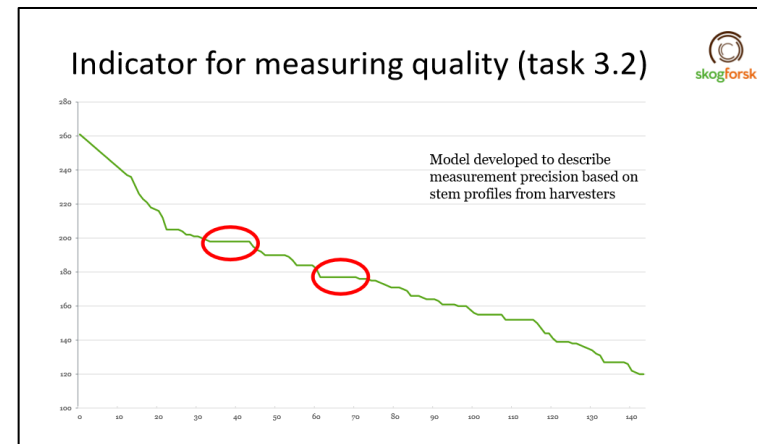
❖ List of advantageous and disadvantageous work patterns

- A comprehensive list of „beneficial“ and „negative“ machine operator behaviour and teamwork aspects was collected via operator interviews in three countries

Results – Aids for detection

❖ Diameter measuring accuracy algorithm

- An algorithm detects inaccuracies in stem diameter measurements of harvester heads in real-time



❖ LiDAR sensor

- A LiDAR sensor was developed to detect the machines environment as well as machine position and movement



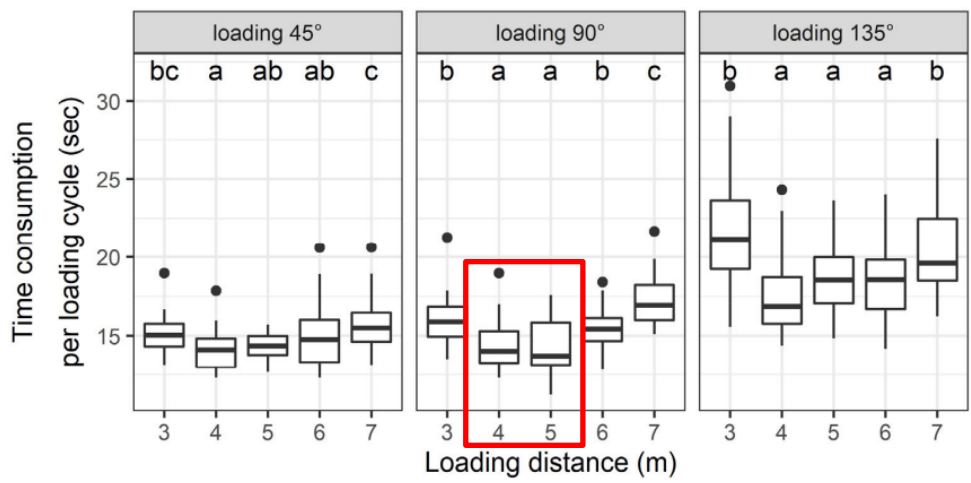
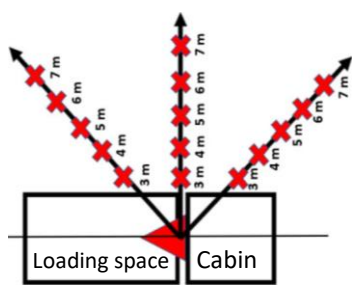
Photo: UGoe Sensor: NIBIO



Results – Work optimisation

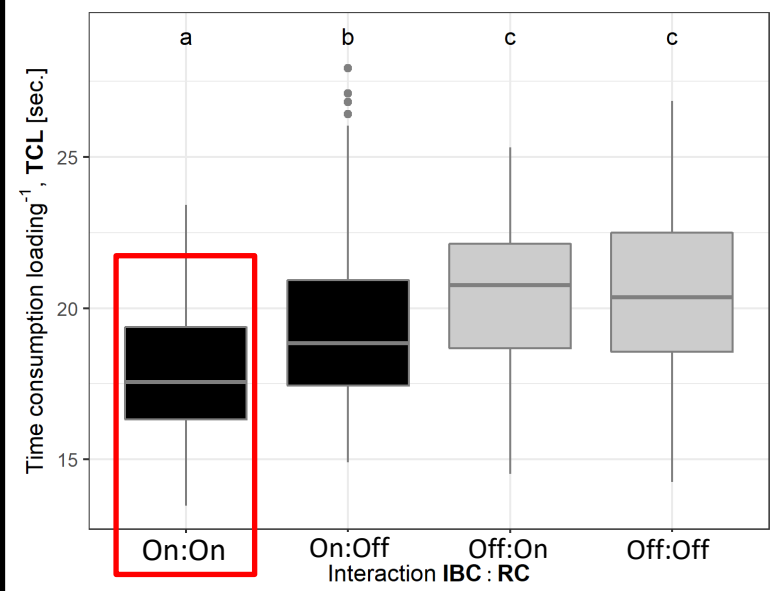
❖ Optimal working angles, distances and log orientations for forwarders

Impact of loading distance and crane angle on forwarder loading cycle durations [sec.]



Hartsch et al. (2022)

Impact of intelligent boom control (IBC) and rotating cabin (RC) on forwarder loading cycle durations [sec.]



Hartsch et al. (2022, pending)

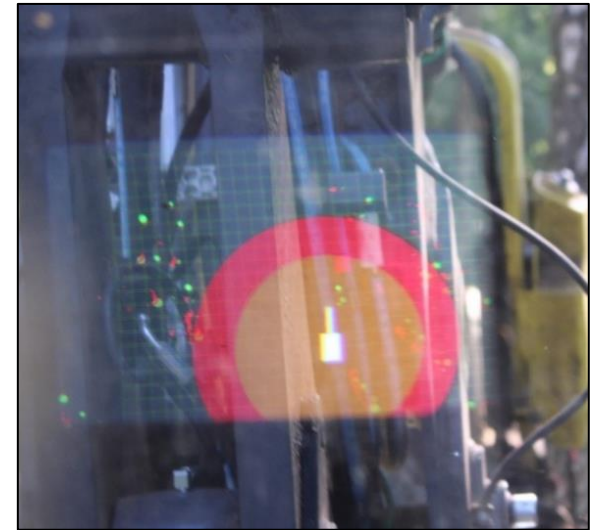
Results – Proof of concept

❖ Final field trials in Germany

- Pilot study for LiDAR system under German forest conditions
- Pilot study for head-up display in the cabin



Head-up display in John Deere Harvester during harvesting operation and display content provided by the LiDAR.



Unexpected peculiarities / barriers

❖ Challenges:

- Unwillingness of machine manufacturers to provide access to CAN-Bus data.
- The shortage of sufficient computational power (computer chip shortage due to COVID-19 crisis) for live data collection, computation and projection on the head-up display

❖ Solution strategy:

- Omit work phase detection based on CAN-Bus data
- Use of external LiDAR System to additionally detect crane position

❖ Compromise:

- Could only collect and save data from LiDAR during harvest for post-hoc computation, but no live depiction on head-up display

Impacts

- ❖ **Deep understanding of work patterns and performance factors**
 - This could help to further develop and improve operator assistance and reduce mental workload for machine operators
- ❖ **Technical feedback in forest machines by head-up displays**
 - After our first trials with head-up displays we can go on to make it a standard equipment in forest machines
- ❖ **Concept of Digital Coach for machine operators developed**
 - The drafted design could now be transformed into a real Digital Coach for machine operator support, steady customised feedback and performance improvement

The value of scientific cooperation

- ❖ **Base for competence network and future collaboration of partners**

For:

- Tackling of problems by utilising diverse competencies of project partners
- Synergies by combining regional perspectives for robust and upscalable solutions

Thank you!

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